

Towards Formal Analysis of Cyber-physical Systems Security

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- Background: Hybrid and Cyber-physical Systems
- Challenges and opportunities
- State of the Field
- Our Approach
- Research Plan
- Outcomes

- Hybrid System
 - System with discrete and continuous components
 - Governed by digital logic and differential equations
- Cyber-physical System
 - Networked hybrid system
 - Examples:
 - Medical monitoring
 - Autonomous vehicles
 - Distributed robotics
 - Critical infrastructure

- Theory
 - CPS include both discrete and continuous components
 - Systems composed by networks
- Simulation
- Metrics

- Hybrid Automata (Alur, Henzinger, et al.)
 - Labeled state transition system
 - Continuous *flow conditions*
 - Discrete *init* and *jump conditions*
 - Strengths: Well-studied and fitted to real systems
 - Weaknesses:
 - High dimensionality quickly leads to intractability
 - No topological (network-like) composition
- Others
 - Hybrid I/O Automata (Lynch)
 - Hybrid Process Algebra (Bergstra, et al.)

- Study “real” systems
 - Model systems we can build and run in our lab
 - Critical infrastructure
 - Automotive
- Integrate network communication into hybrid automata composition
- Study how changes in the “cyber” portion of CPS influence real world

- Identify suitable formalism for network modeling
- Fix target application domain
 - Automotive, critical infrastructure, medical
 - Linear, elliptical, etc. differential equations in continuous space
- Select desired analytical properties of the system
- Build network composition framework

- Formal theoretical framework for modeling CPS
- Execution model or simulation environment
- Metrics specifications
- Niche checking/audit tools
 - Field-deployable application to make FM-backed reports about its environment

Problem Need to model cyber-physical systems

Prior Work Focuses on isolated hybrid systems

Opportunities Unfilled niche for comprehensive formal CPS model

Our role Unite hybrid systems and networking formalisms

Main message **Model the network**